





Kernel Dimension Matters: to Activate Available Kernels for Real-time Video Super-Resolution

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Motivation

> It is crucial to split channels with dynamic and static information for efficient processing, which represents the redundant complements and temporal offsets respectively.

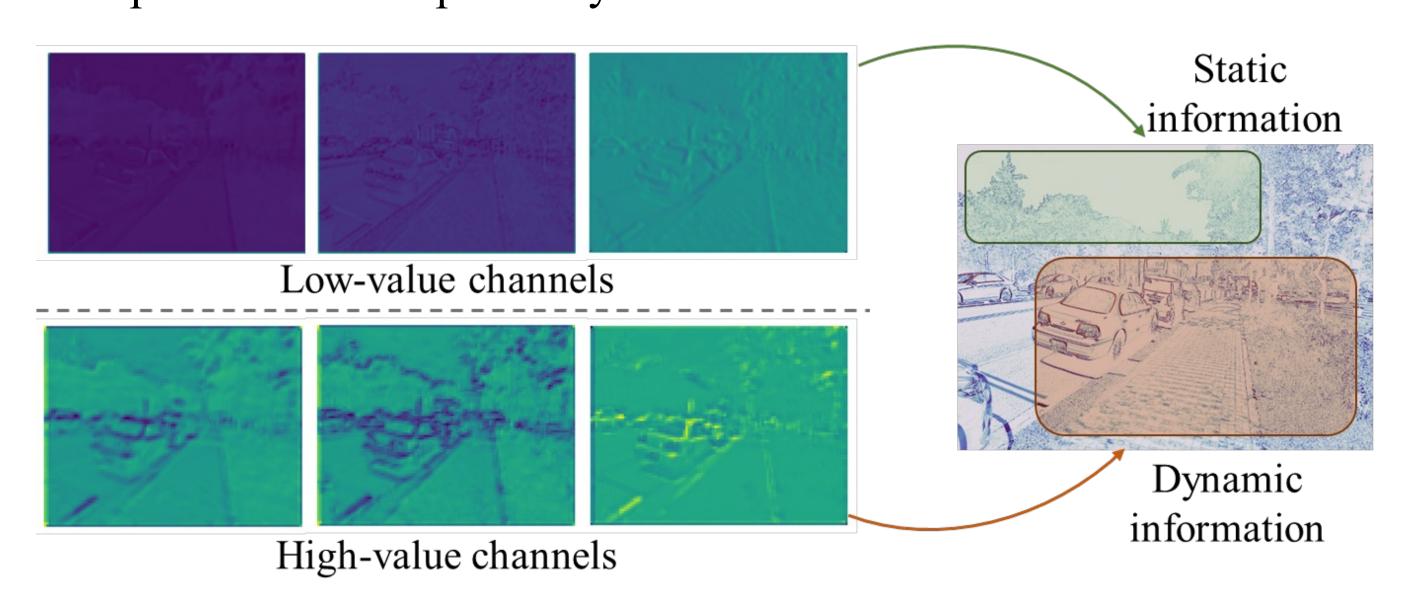


Fig.1 Different value channels.

Contribution

- > We propose a Kernel Split Network (KSNet) for RTVSR, including bidirectional unidirectional paradigms, recurrent which reconstructs the 720 × 1080 video with 31 ms/frame and achieve superior results over other SOTA methods.
- > We design a kernel-split strategy to discriminate the channels of highvalue and low-value, and apply the re-parameterized convolutions on the high-value channels. This strategy enables the exploration of highvalue dynamic information and the representation of convolution layers, while reducing the dimensional complexity.
- > We adopt multiple flows on the deformable alignment module to light the training burden of the deformable convolution and enhance the motion representation with affordable calculation costs.

Methodology

Figure Given a sequence of LR frames $\{x_1, x_2, ..., x_n, ..., x_N\}$ where $x_n \in$ $\mathbb{R}^{C \times W \times H}$, the HR frames $\{y_1, y_2, ..., y_n, ..., y_N\}$ are constructed in a frame-to-frame pipeline. The input frames are propagated in the first recurrent branch (green area) and then refined in the other recurrent branch (blue area).

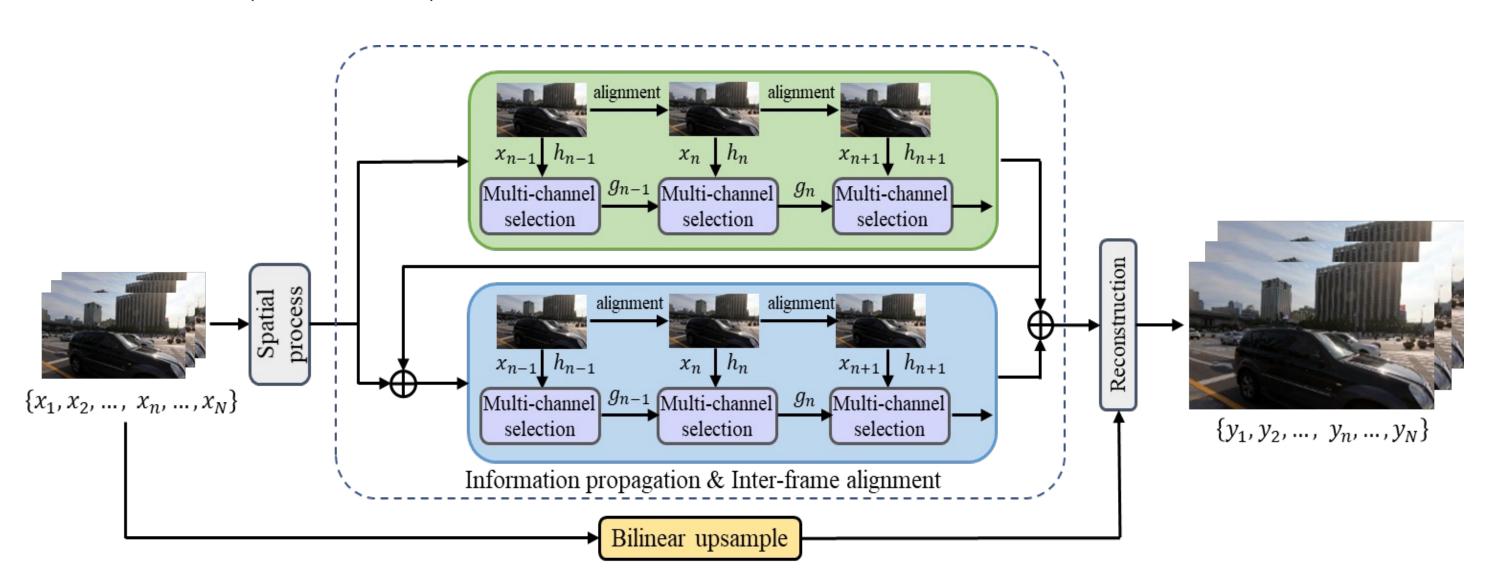


Fig.2 Overview of Kernel Split Network (KSNet).

➤ Multi-channel Selection Unit (MSU)

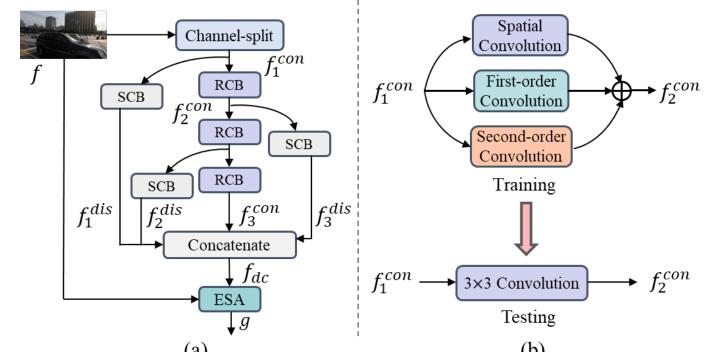


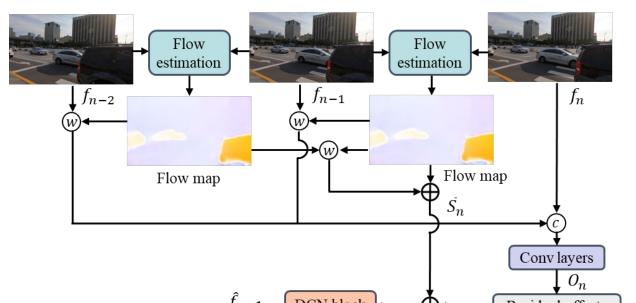
Fig.3 Multi-channel Selection Unit.

MSU splits the high-value and low-value channels to merge the kernel dimensions hierarchically.

 $\sigma_2(\sigma_1(k)) = W_2*(W_1*k+B_1) + B_2$

$$egin{aligned} W_{ ext{pr}}^{:,,i+igl\lfloorrac{H-h}{2}igr
floor,j+igl\lfloorrac{W-w}{2}igr
floor}&=W_{ ext{ps}}^{:,,i,j}\ B_{ ext{pr}}&=B_{ ext{ps}} \end{aligned} egin{aligned} W_{ ext{ps}}&=B_{ ext{ps}} \end{aligned} egin{aligned} W_{ ext{ps}}&=W_{ ext{p}}+W_{ ext{one}}+W_{ ext{sec}}\ B_{ ext{ps}}&=W_{ ext{p}}+B_{ ext{one}}+B_{ ext{sec}} \end{aligned}$$

> Multiple Flow Deformable Alignment (MFDA)



MFDA aligns the motion area, where the optical flow is viewed as residual offsets for deformable $egin{aligned} s_{n
ightarrow n-1} &= \operatorname{ME}(f_n, f_{n-1}) \ s_{n-1
ightarrow n-2} &= \operatorname{ME}(f_{n-1}, f_{n-2}) \end{aligned}$ alignment.

 $ar{s}_n = s_{n o n-1} + ext{MC}(s_{n-1 o n-2}, s_{n o n-1}) \hspace{1cm} O_n = Cig(ext{cat}ig(ar{f}_n, f_nig)ig)$

Fig.4 Multiple Flow Deformable Alignment. $\bar{f}_n = \text{MC}(f_{n-2}, s_{n-1 \to n-2}) + \text{MC}(f_{n-1}, s_{n \to n-1})$ $\hat{f}_n = D(O_n + \bar{s}_n)$

(22.11 / 0.7691)

(25.13 / 0.8074)

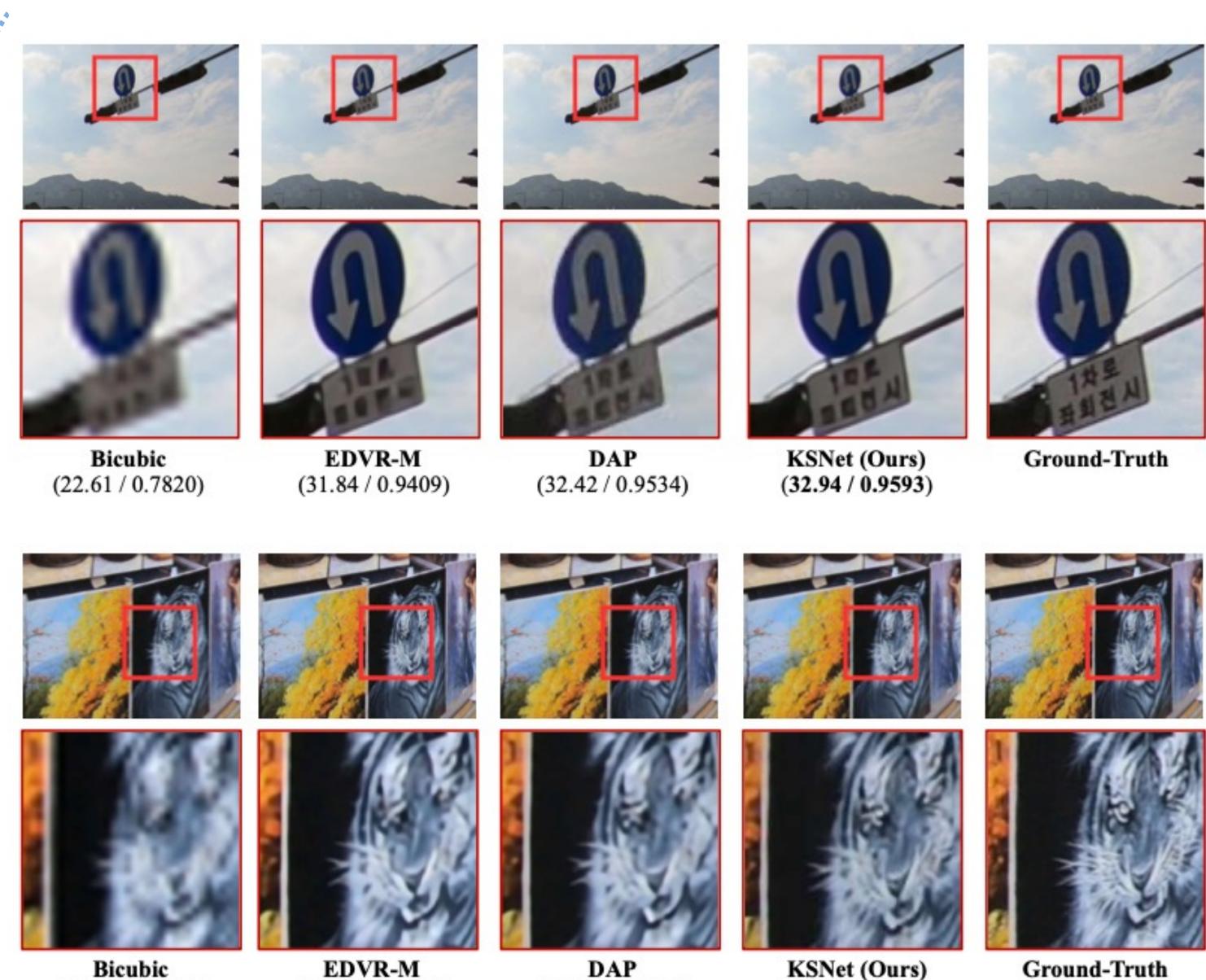


Fig.5 Visual comparisons with SOTA methods on REDS dataset.

(26.74 / 0.9243)

(26.51 / 0.9065)

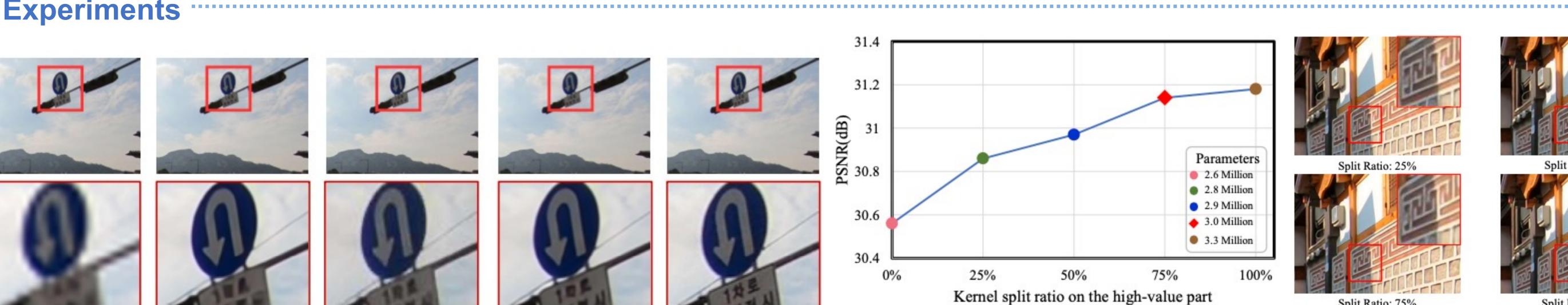
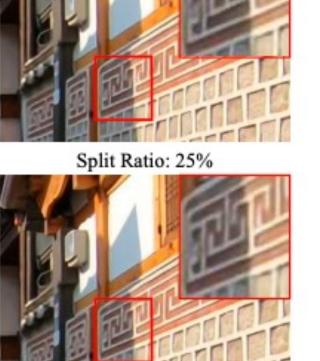
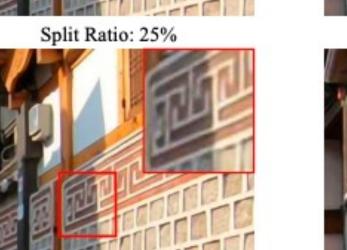


Fig.6 Comparisons on the reconstruction performance and kernel split ratio.



Split Ratio: 75%



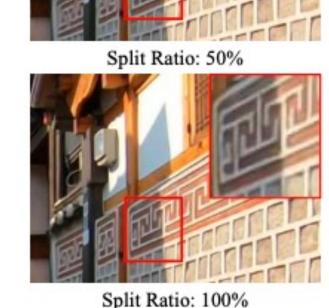


Fig.7 Comparisons on the visual quality of different split ratios.

Tab.1 Quantitative comparison with different methods.

Methods	Params(M)	FLOPs(G)	fps(1/s)	Run(ms)	Test datasets			
					Vid4	REDS4	Vimeo90K-T	
Bicubic	-	-	-	-	23.78/0.6347	26.14/0.7292	31.30/0.8687	
VESPCN [2]	-	-	28.6	<u>35</u>	25.35/0.7557	-	-	
RLSP [6]	4.2	503.7	21.7	46	27.05/0.8139	-	36.49/0.9403	
RRN [9]	3.4	387.5	22.2	45	27.09/0.8185	-	-	
DAP-128 [5]	-	330.0	26.3	38	-	30.59/0.8703	37.29/0.9476	
RSDN [7]	6.2	713.2	10.6	94	27.22/0.8249	-	37.23/0.9471 37.33/0.9484	
EDVR-M [24]	3.3	925.7	8.6	116	27.10/0.8186	30.53/0.8699		
KSNet-uni (Ours)	3.0	296.9	32.3	31	27.14/0.8208	30.69/0.8724	37.34/0.9490	
ASSL-bi [34]	2.7	210.2	32.3	31	27.03/0.8163	30.72/0.8783	36.71/0.9410	
RSCL-bi [26]	2.7	210.2	32.3	31	27.16/0.8213	30.99/0.8831	36.83/0.9421	
BasicVSR [3]	6.3	330.0	15.9	63	27.24/0.8251	31.42/0.8909	37.53/0.9450	
KSNet-bi (Ours)	3.0	<u>296.9</u>	32.3	31	27.22/0.8245	31.14/0.8862	37.54/0.9503	

Tab.2 Ablation study on re-parameterization strategy.

		J	1				
Model	Params-training(M)	Params-testing(M)	FLOPs-training(T)	FLOPs-testing(T)	Run(ms)	fps(1/s)	PSNR(dB)
KSNet-uni-plain	2.9	2.9	296.9	296.9	31	32.3	30.50
KSNet-bi-plain	2.9	2.9	296.9	296.9	31	32.3	30.94
KSNet-uni (Ours)	3.4	2.9	320.9	296.9	31	32.3	30.69
KSNet-bi (Ours)	3.4	2.9	320.9	296.9	31	32.3	31.14